

Simulation of extreme European heat waves with rare event algorithms

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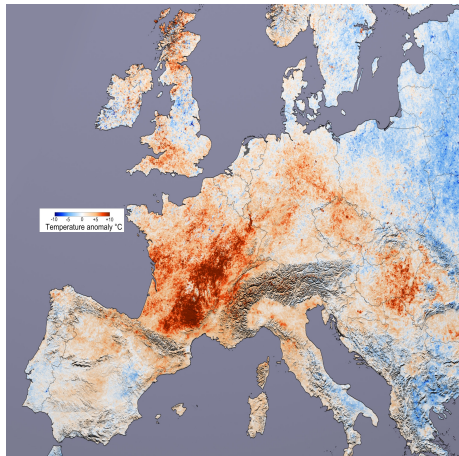


Outline

- 1 Extreme events sampling and motivation
- 2 Background
 - Importance sampling
 - Large deviation framework
 - Giardina-Kurchan-Tailleur-Lecomte algorithm
- 3 Application to heat waves with a GCM (Plasim)
 - Model setup
 - Results in large deviation limit
 - Results for seasonal time scales
- 4 Conclusions and perspectives

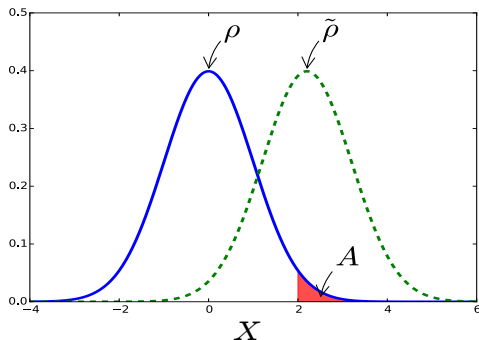
Extremely rare heat waves

- Europe 2003, Russia 2010: estimated return times of several decades or hundreds of years;
- To obtain reliable estimates we need very long, expensive simulations;
- Attribution to climate change uncertain (also) for lack of statistics.



European heat wave of summer 2003

Importance sampling for rare events

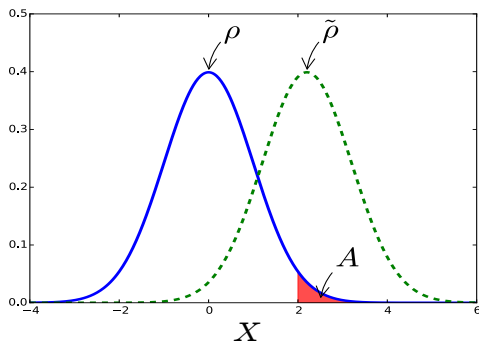


$$\gamma_A = \int dx \rho(x) 1_A(x) \rightarrow \hat{\gamma}_A = \frac{1}{N} \sum_{i=1}^N 1_A(X_i)$$

vs

$$\gamma_A = \int dx \tilde{\rho}(x) L(x) 1_A(x) \rightarrow \hat{\gamma}_A = \frac{1}{N} \sum_{i=1}^N L(\tilde{X}_i) 1_A(\tilde{X}_i)$$

Variance reduction



$$\hat{\gamma}_A = \frac{1}{N} \sum_{i=1}^N 1_A(X_i) \rightarrow \frac{1}{\gamma_A} \sqrt{\frac{\text{Var}(\hat{\gamma}_A)}{N}} \approx \frac{1}{\sqrt{\gamma_A N}}$$

vs

$$\hat{\gamma}_A = \frac{1}{N} \sum_{i=1}^N L(\tilde{X}_i) 1_A(\tilde{X}_i) \rightarrow \frac{1}{\gamma_A} \sqrt{\frac{\text{Var}(\hat{\gamma}_A)}{N}} = \sqrt{\frac{\mathbb{E}[L(x) 1_A(x)] - \gamma_A^2}{\gamma_A^2 N}}$$

Rare event algorithms, how to choose them

- In a dynamical system we need to take into consideration the **dynamics**: importance sampling or other approaches must be applied at the level of the trajectories
- The choice of the algorithm must reflect the properties of the extreme event under consideration. Heat waves are a case of extreme event characterized by **time persistence**
- Statistically, we can approach this in (at least) two ways: clustering of extremes, or tails of distributions of time averages. Second approach leads us to **large deviation theory**

Donsker-Varadhan large deviation framework

- Large time asymptotics for time averaged observables

$$\rho\left(\frac{1}{T}\int_0^T f(x(t))dt = a\right) \underset{T \rightarrow \infty}{\asymp} Ce^{-TI(a)}.$$

where $I(a)$ is called **rate function** (e.g. *Touchette 2009*).

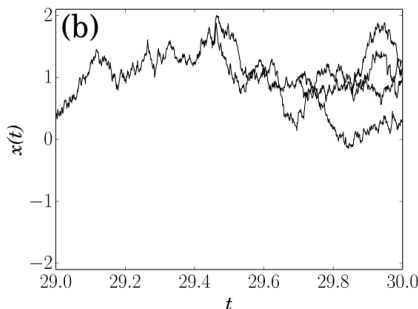
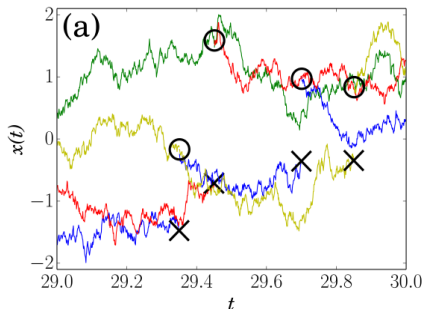
- Linked to the **scaled cumulant generating function** (SCGF)

$$\lambda(k) = \lim_{T \rightarrow +\infty} \frac{1}{T} \log \left(\mathbb{E}[e^{k \int_0^T f(x(t))dt}] \right)$$

by the Gärtner-Ellis theorem $I(a) = \sup_a \{ka - \lambda(k)\}$.

- **Giardina-Kurchan-Tailleur-Lecomte algorithm** (GKTL): rare event algorithm designed to evaluate large deviation functions

Giardina-Kurchan-Tailleur-Lecomte (GKTL) algorithm



Ensemble of N trajectories $x_n(t)$, **target observable** $f(x(t))$. At times $t_j = j\tau$ each trajectory produces a number of copies of itself proportional to

$$w_n^{k*}(t_j) = \frac{1}{R_j^{k*}} e^{k* \int_{t_{j-1}}^{t_j} f(x_n(t)) dt}, \quad \text{with} \quad R_j^{k*} = \frac{1}{N} \sum_{n=1}^N e^{k* \int_{t_{j-1}}^{t_j} f(x_n(t)) dt}$$

Effective ensemble reconstructed tracing back the history of the survivors.

GKTL algorithm and importance sampling

- The GKTL algorithm gives an unbiased estimator of the SCGF

$$\lambda(k^*) = \lim_{T_a \rightarrow +\infty} \frac{1}{T_a} \sum_{j=1}^{T_a/\tau} \log R_j^{k^*}$$

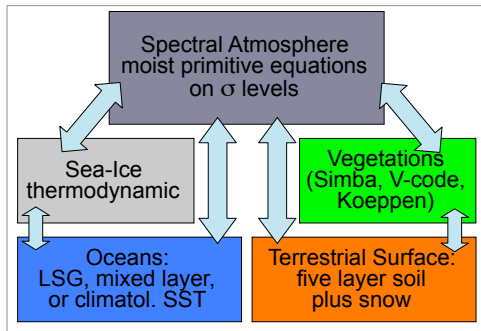
for arbitrary values of k^* , hence fluctuations a in large deviation limit.

- It generates **importance sampling of trajectories**

$$\mathbb{P}_{k^*} \left(\{x(t)\}_{0 \leq t \leq T_a} \right) \underset{N \rightarrow \infty}{\sim} \frac{e^{k^* \int_0^{T_a} f(x(t)) dt}}{\mathbb{E} \left[e^{k^* \int_0^{T_a} f(x(t)) dt} \right]} \mathbb{P}_0 \left(\{x(t)\}_{0 \leq t \leq T_a} \right)$$

up to errors of order $1/\sqrt{N}$ on expectation values (*Del Moral 2004*).

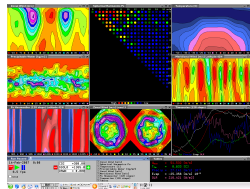
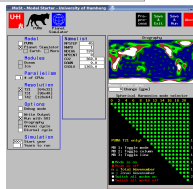
Plasim, advertisement slide



Key features

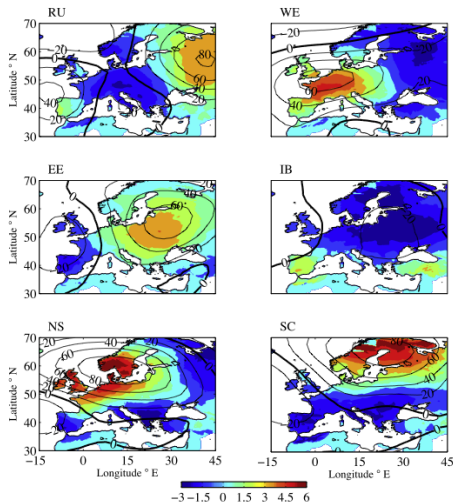
- portable
- fast
- open source
- parallel
- modular
- easy to use
- documented
- compatible

Model Starter
and
Graphic User Interface



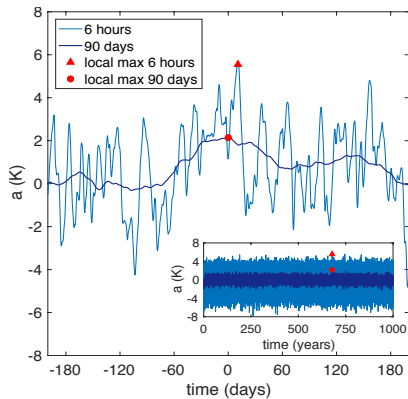
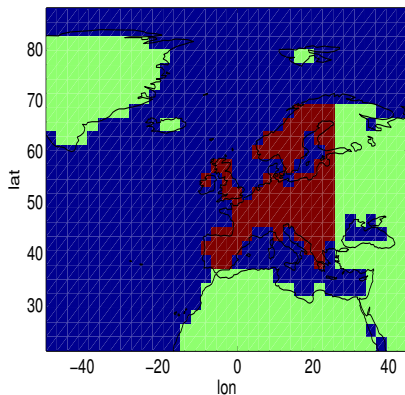
European heat waves classification

- Typically mid-latitude blocking, persistent anticyclonic anomaly leading to surface warming
- Spatial clustering and feedbacks at different scales (hydrological preconditioning, mesoscale effects, etc.)
- Complex picture: we simplify the question at first



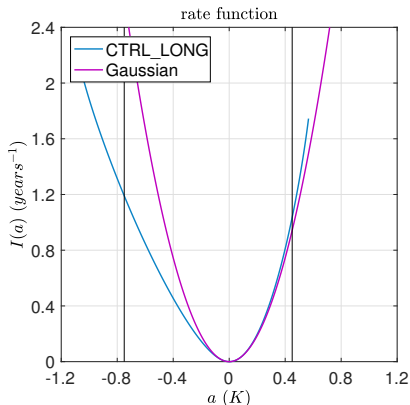
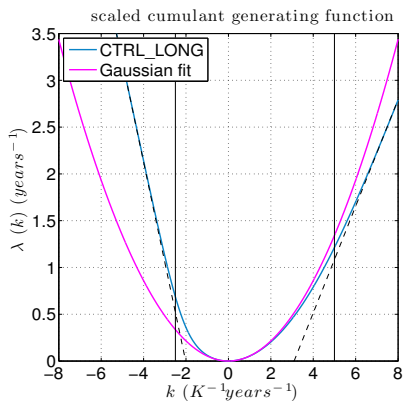
Stefanon et. al 2012

Model setup and experimental settings



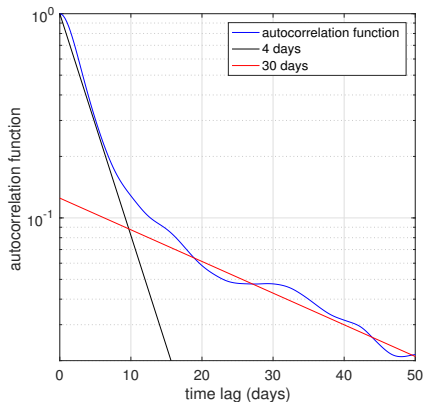
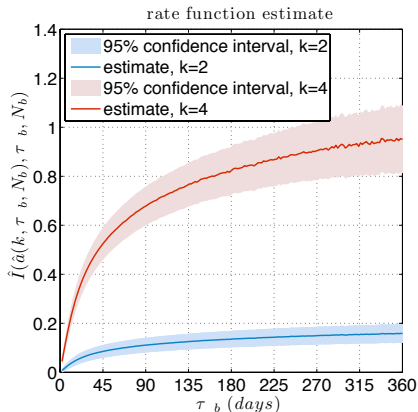
- T42 resolution, 10 vertical layers, $\sim 10^5$ - 10^6 degrees of freedom.
Perpetual summer setup: no daily or seasonal cycle
- Simple indicator of heat waves: fluctuations of **time averages** of western European surface temperature over averaging time T

Direct estimate of large deviation functions



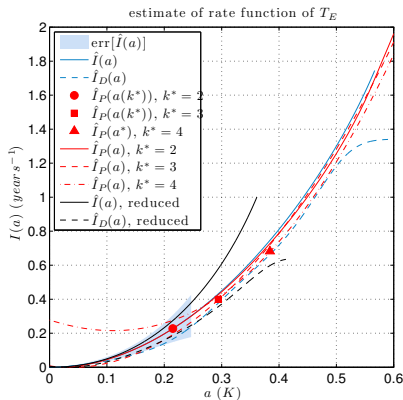
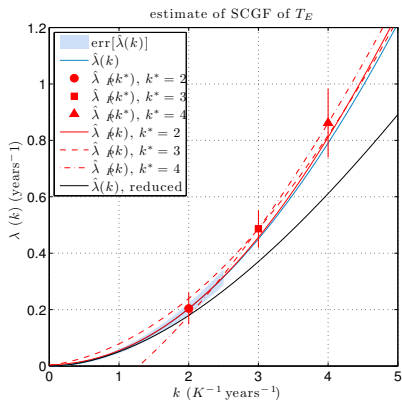
- Direct estimate from 1000 years control run as benchmark
- Barely outside of Gaussian regime for positive anomalies
- Problem: very long time to be in the large deviation limit, $T > 1$ year

Problem: limit not reached for weekly/seasonal averages



- Slow convergence probably related to slow decay of the tail of the autocorrelation function
- Monthly time scale introduced by land surface processes (?)

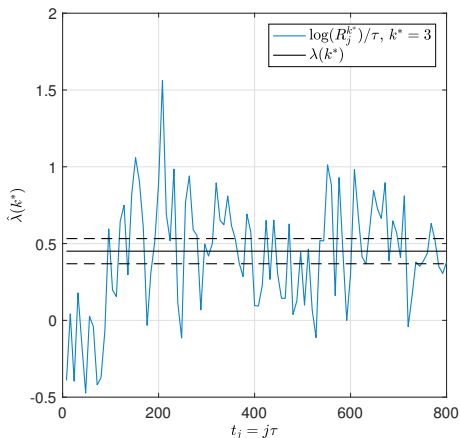
Test of reconstruction of SCGF



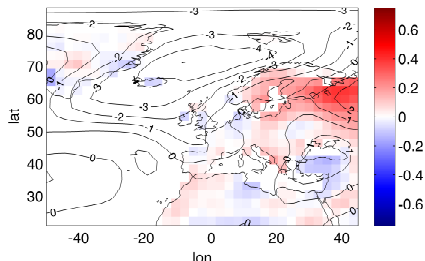
- Direct estimate from 1000 years control run as benchmark;
- GKTL gives correct results for smaller cost (~ 284 years);

What is the GKTL algorithm selecting?

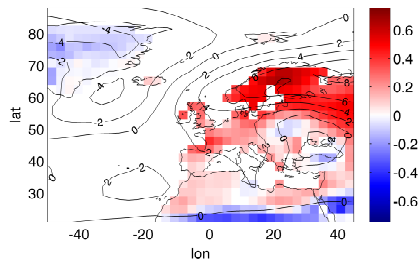
$$\lambda(k^*) = \lim_{T_a \rightarrow +\infty} \frac{1}{T_a} \sum_{j=1}^{T_a/\tau} \log R_j^{k^*}$$



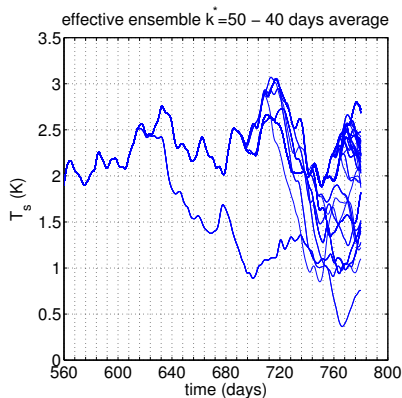
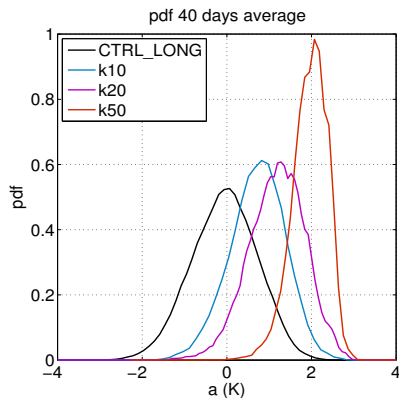
GK $k^*=3$ - anomalies T_s and 500 hPa gph - days 1-80



GK $k^*=3$ - anomalies T_s and 500 hPa gph - days 721-800

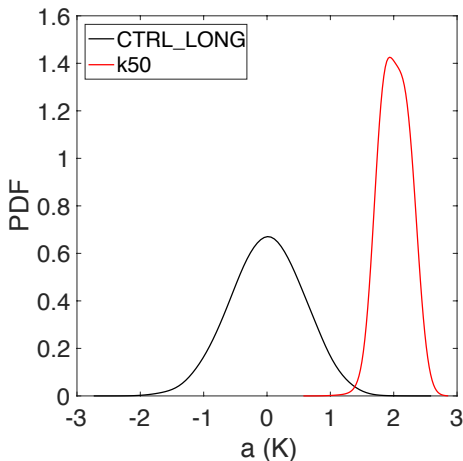


Statistics of shorter time averages



- Needs large values of k , because pdf widens
- For values of k too large, issue with multiplicity of trajectories

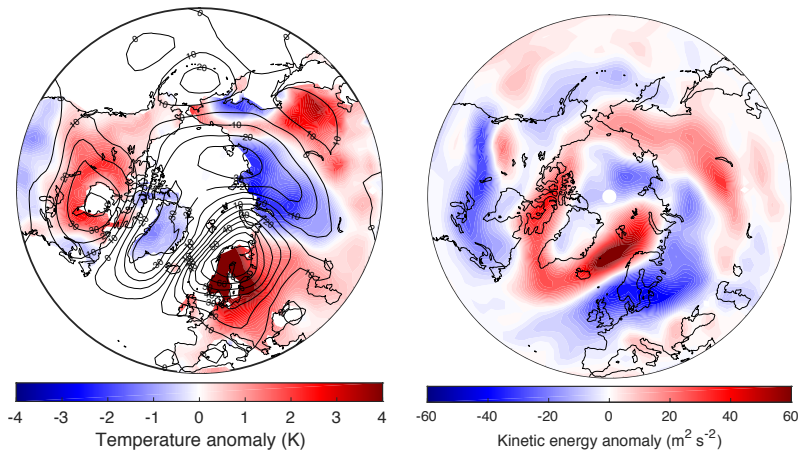
Importance sampling for seasonal time scales



- $T = 90$ days, finite time average not in the large deviation limit
- Compromise between averaging time, length of the trajectories (short) and number of trajectories (large)
- Finding the right balance importance sampling seems to work very well

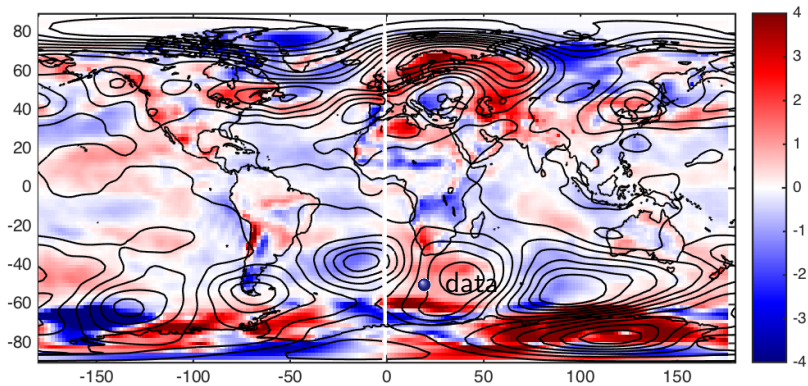
Ragone, Wouters, Bouchet (2018)

Composite analysis for $a > 2 \text{ K}$, teleconnection patterns

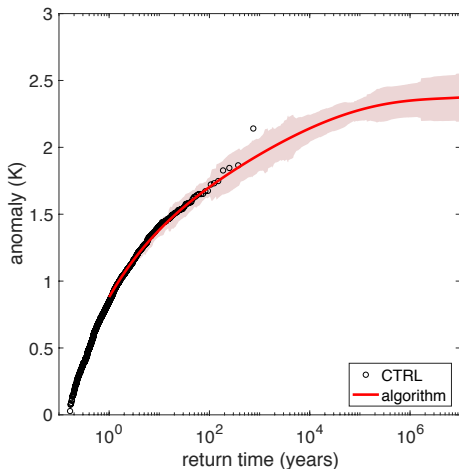


Ragone, Wouters, Bouchet (2018)

- Precise estimate of conditional expectation values (composites);
- "Teleconnection" patterns with northward displacement of jet stream.



Return times of 90 days average temperature anomalies



- Return time of 90 days average European temperature;
- Same computational cost (1000 years) for direct and GKTL;
- Precise estimates of return times of millions of years with costs orders of magnitude smaller.

Ragone, Wouters, Bouchet (2018)

Conclusions and work in progress

Conclusions

- The GKTL algorithm seems to be effective to oversample heat waves
- This could open a new range of dynamical studies with GCMs

Work in progress

- Extend to systems with time dependent forcings (seasonal cycle!)
- Dynamical studies: relation with blocking events? Which physical feedbacks?

Next

- Combination with other methods, like analogues?
- This is ok for time persisting phenomena, but what about instantaneous extremes?

References

This work

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GKTL algorithm

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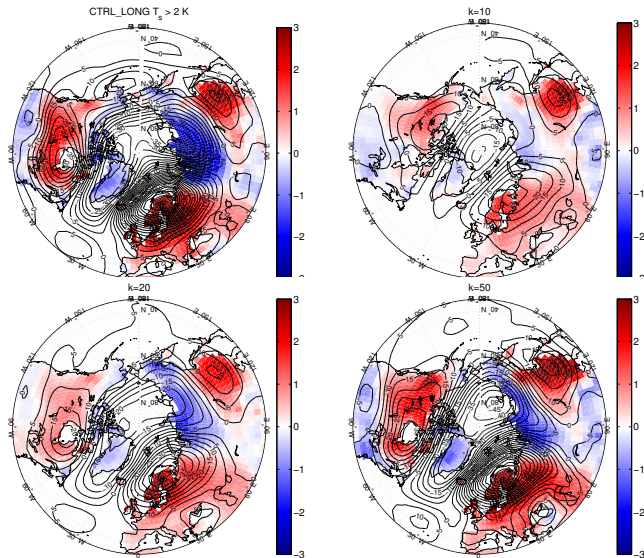
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Heat waves

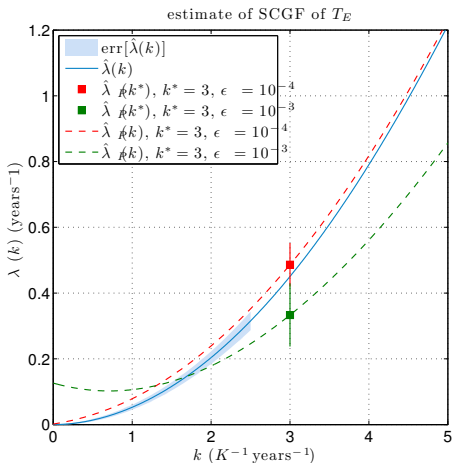
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Composite average for $T_s > 2\text{ K}$ and GKTL climate

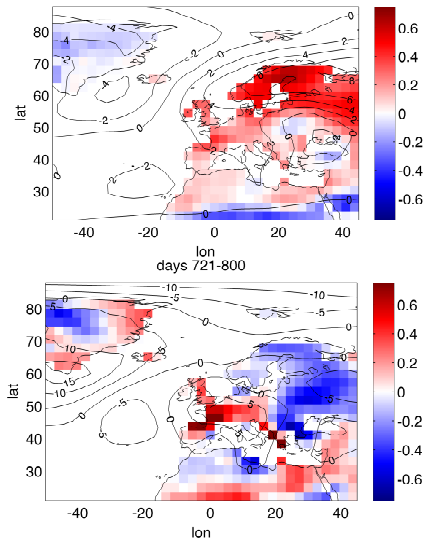


Sensitivity: increased perturbation intensity

We set $\epsilon = 10^{-3}$ instead of $\epsilon = 10^{-4}$



GK $k^*=3$ - anomalies T_s and 500 hPa gph - days 721-800



Sensitivity: changing the cloning time? (to do)

